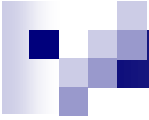


A Neurophysiological Model of Grammatical Construction Processing with Cross-Linguistic Validation and Robotic Implementation

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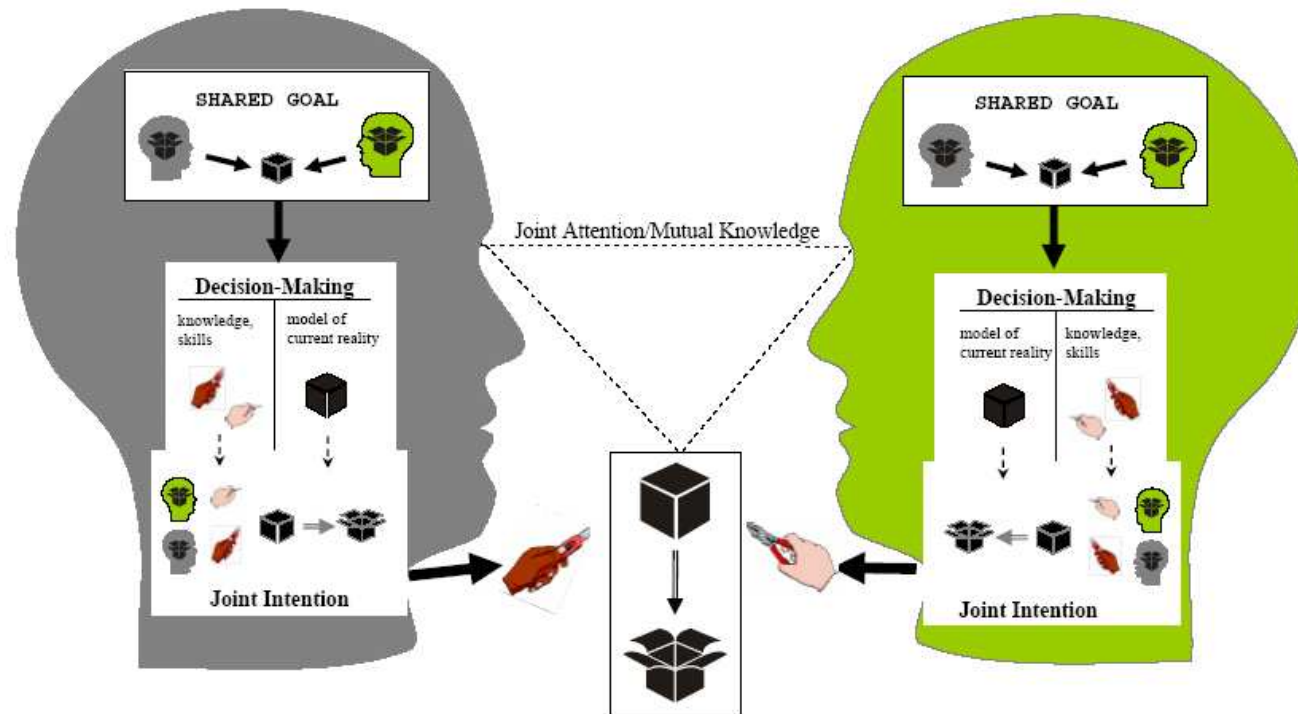


A Cognitive Systems Approach to Language

- Requirements on language: what is it for?
- What strategies can be employed?
- How can this be realized in neurophysiology?
- A Model of Grammatical Construction Processing
- How can the model access « meaning »?
- Language in the context of Cooperation
- Perspectives

What is language for?

Sharing Mental States



Tomasello M, Carpenter M, Call J, Behne T, Moll HY (2005) **Understanding and sharing intentions: The origins of cultural cognition**, Beh. Brain Sc;. 28; 675-735.

Requires a linearization of complex multidimensional representations



What encoding strategies can be employed?

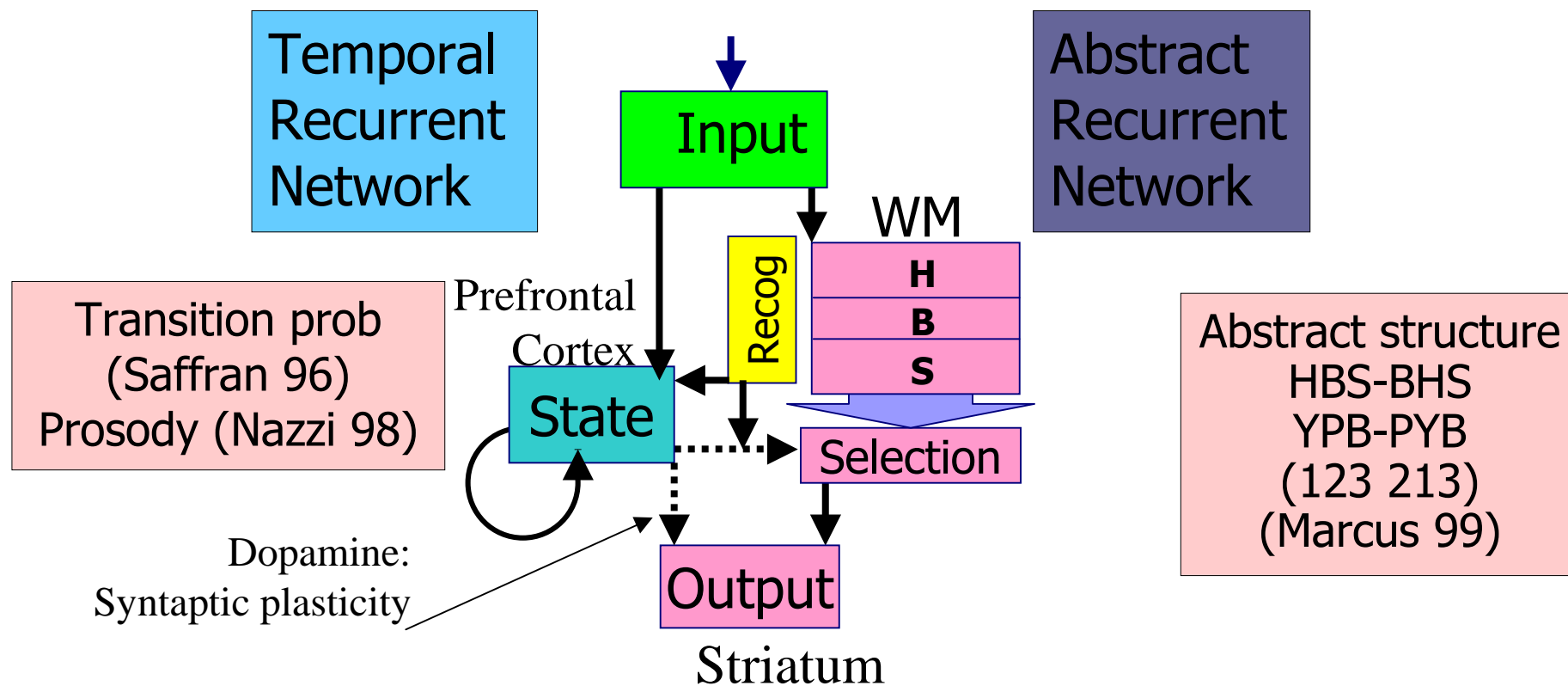
- In the morphosyntactic arena, there is an item-based competition between word orders and grammatical markings centered on valence relations.
- At the core of syntactic processing is the learning and use of item-based constructions
 - children first learn that a verb like *throw* takes three arguments (thrower, object thrown, recipient)
 - by comparing groups of these item-based patterns through analogy, children can then extract broader class-based patterns

Competition Model - MacWhinney 2004, Bates & MacWhinney 1987

Usage Based Learning – Tomasello 2003

Construction Grammar – Goldberg 1999

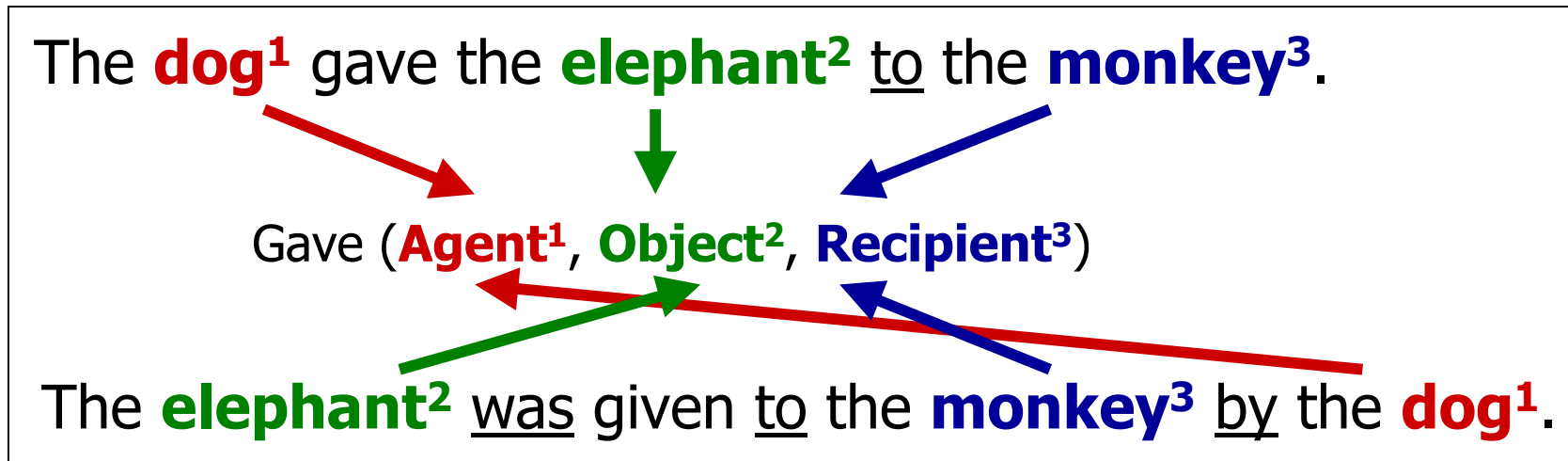
Neurophysiology of Serial, Temporal and Abstract Sequences



Dominey, P. F., & Ramus, F. (2000). Neural network processing of natural language: I. Sensitivity to serial, temporal and abstract structure of language in the infant. *Language and Cognitive Processes*, 15(1), 87–127.

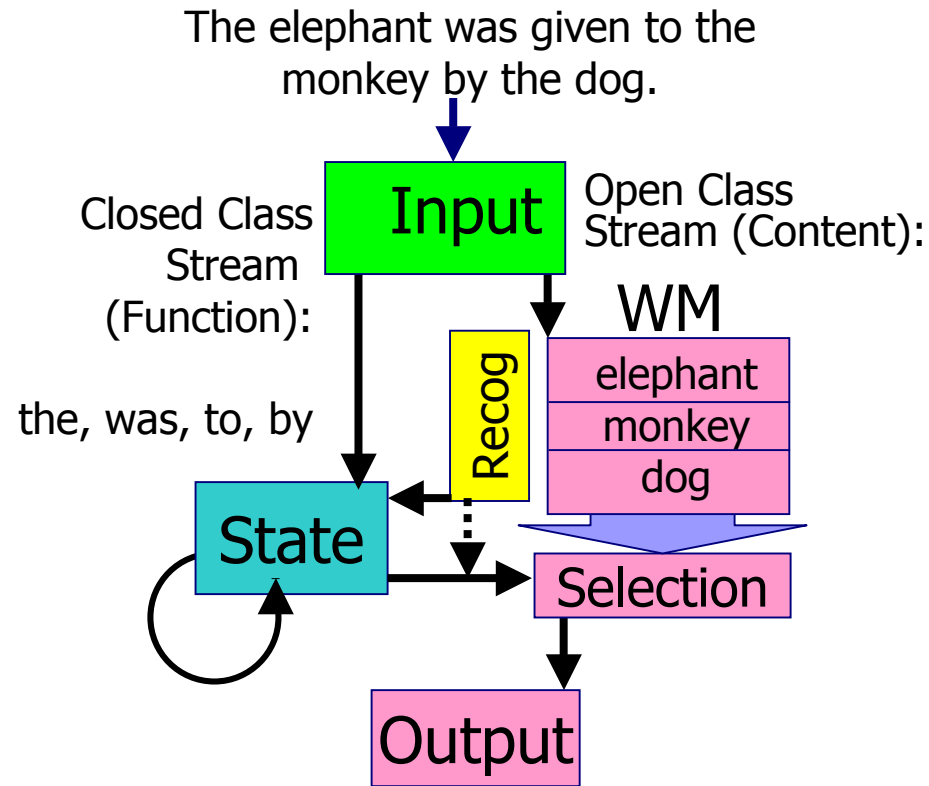
(Dominey et al. J Cognitive Neuroscience 1995, 1998)

Extension of Abstract Structure to Grammatical Constructions



- Different surface forms map to same meaning
- Indicated by function words (was, to, by)
- Non-Linguistic correlate – “equivalence hypothesis”
 - 123X123, 231Y123

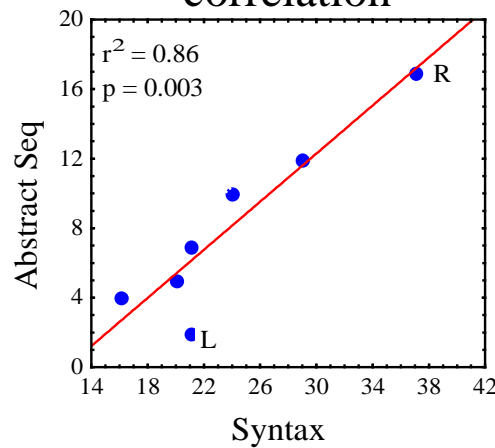
Abstract sequencing model learns grammatical constructions



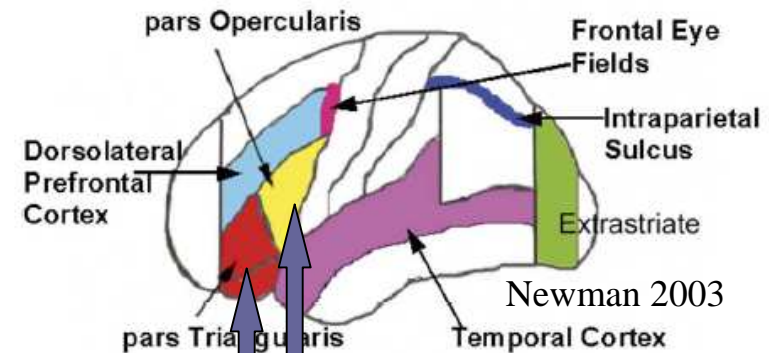
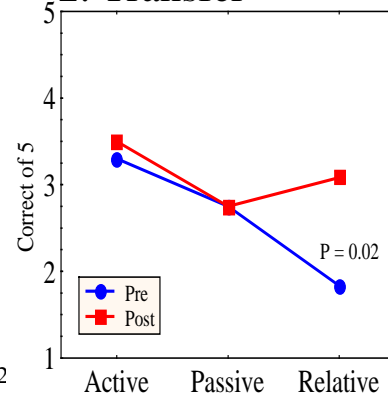
Canonically ordered nouns:
agent(dog), object(elephant),
recipient(monkey)

Validating the 'Equivalence Hypothesis'

1. Agrammatic correlation

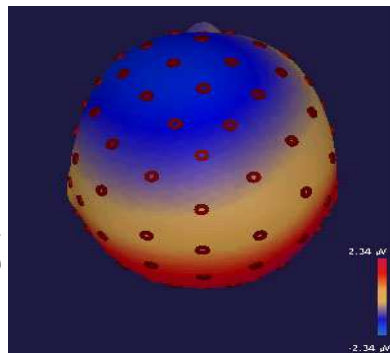


2. Transfer

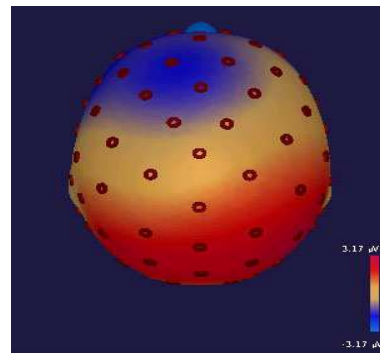


Newman 2003

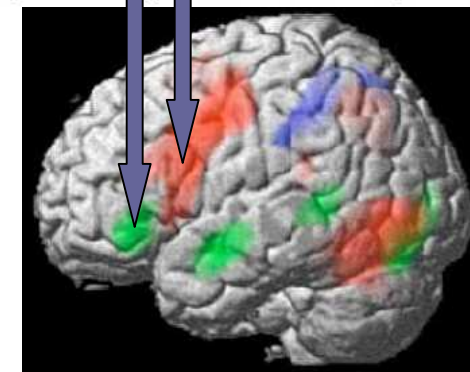
3. ERP



Language



Sequences

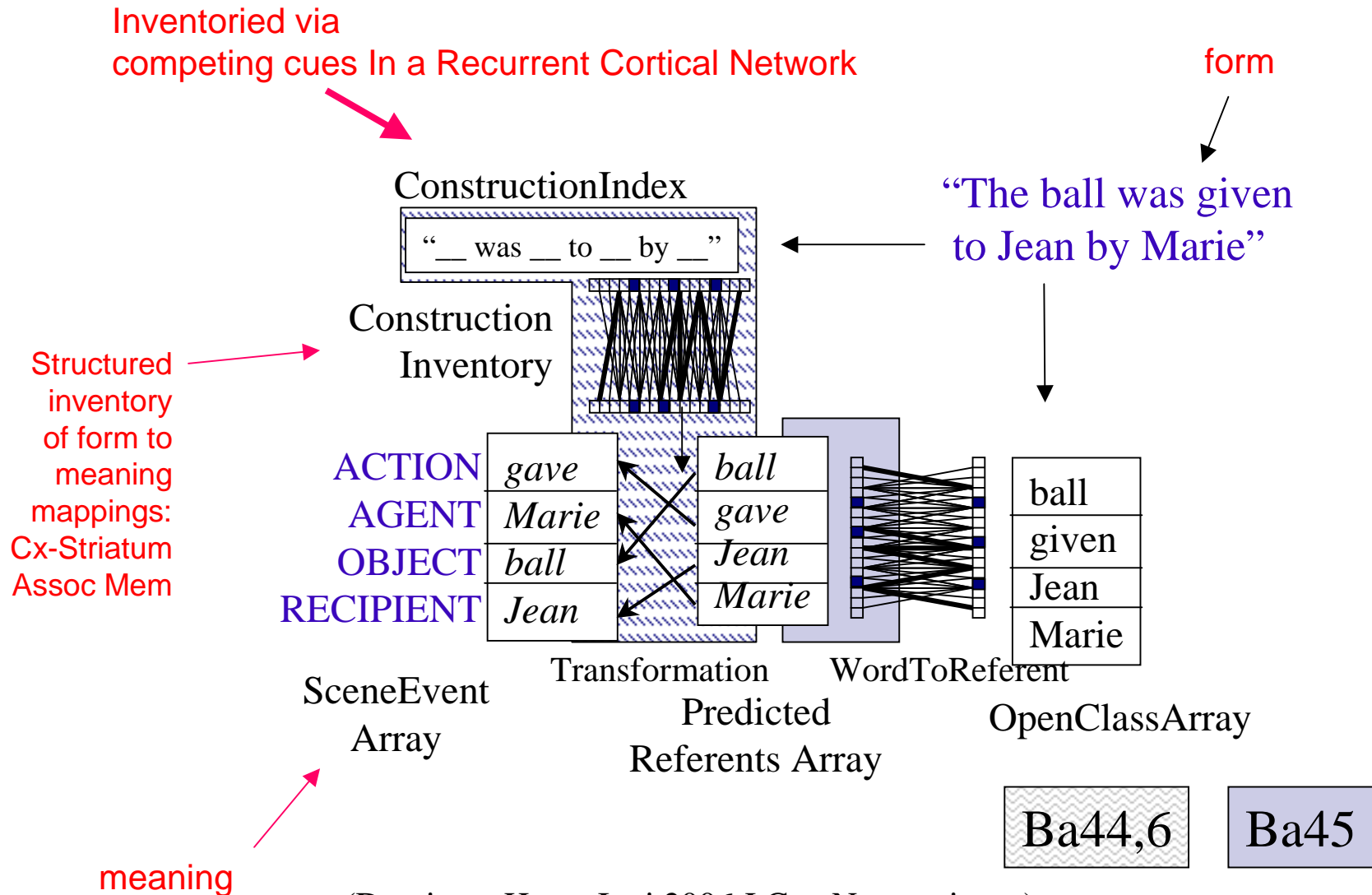


4. fMRI

Language Language & Seq

4. Hoen, Dominey et al Cortex 2006

A Neurolinguistic Model of Grammatical Construction Processing



(Dominey, Hoen, Inui 2006 J Cog Neuroscience)



Cross-Linguistic Validation: Japanese

Block-**ga** circle-**wo** oshita triangle-**ni-yotte** tatakareta.

Circle-**wo** oshita triangle-**ni-yotte** block-**ga** tatakareta.

The block was hit by the triangle that pushed the circle.

Pushed(triangle, circle), Hit(triangle, block)

Circle-wo tataita block-ga triangle-ni-yotte osareta.

Triangle-ni-yotte circle-wo tataita block-ga osareta.

The block that hit the circle was pushed by the triangle.

Hit(block, circle), Pushed(triangle, block)

Block-ga circle-wo oshita triangle-wo tataita.

Circle-wo oshita triangle-wo block-ga tataita.

The block hit the triangle that pushed the circle.

Pushed(triangle, circle), Hit(block, triangle)

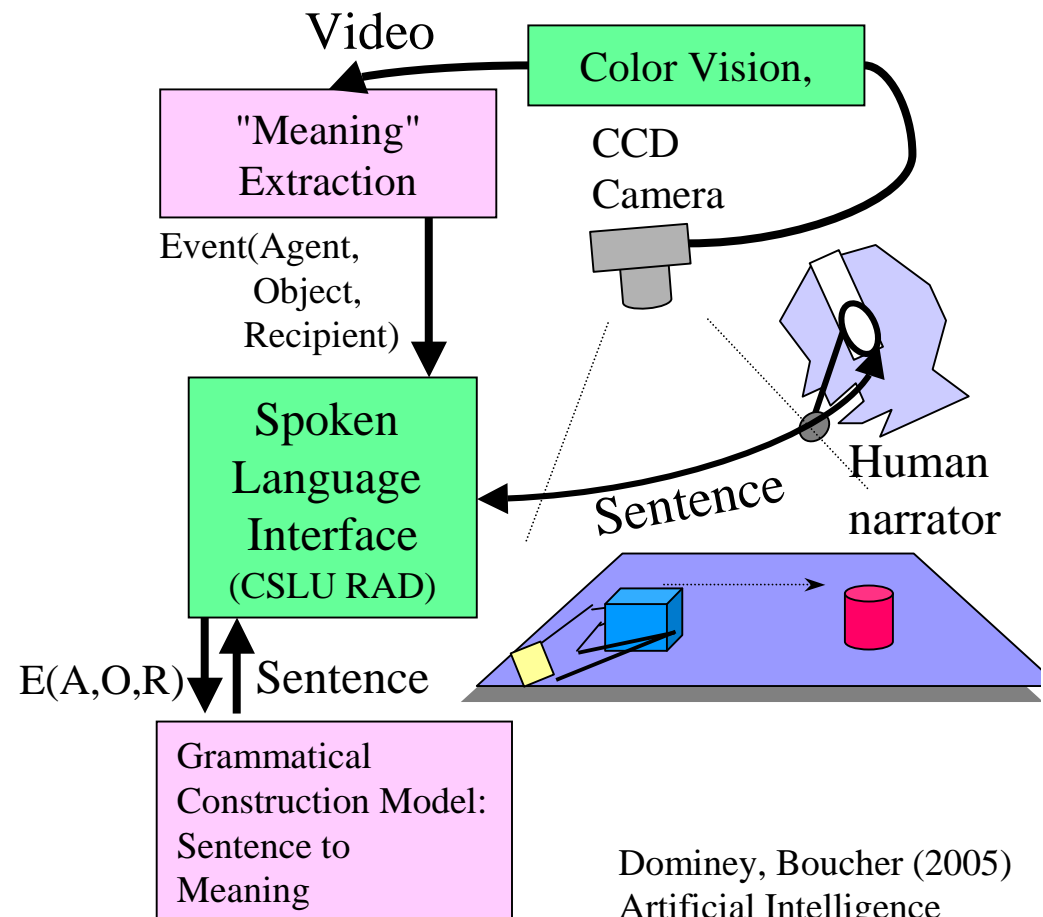
N = 26 constructions

Dominey & Inui CoLing 2004

Dominey, Hoen, Inui JoCN 2006

Towards Grounded Meaning: Linking Language to Action

- “Perceptual Processing”
 - Color based segmentation
 - Speech recognition, syntheses, dialog mgmt (CSLU RAD)
- “Cognitive Processing”
 - Extraction of “Meaning” : Action Perception
 - Events from spatiotemporal schemas
 - Sentence-Meaning mapping
 - Grammatical Constructions

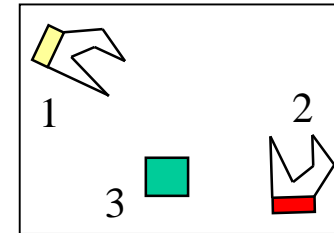


Dominey, Boucher (2005)
Artificial Intelligence

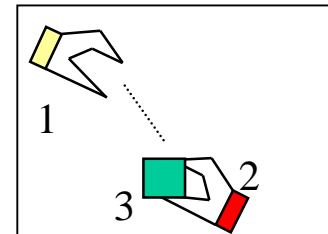
Action Perception: Extracting meaning from vision

- Events categorized in terms of perceptual primitive “contact”
 - *contact(agent, objet, duration)*
 - *Position, velocity*
- Single-contact events
 - *touch, push, take* can be described as contacts, and durations.
 - duration: *Touch < Push < Take*
 - Agency = $f(\text{relative velocity})$
- Multiple-contact events
 - *Give(agent, object, recipient)*
 - *Take(agent, object, recipient)*

Give(2, 3, 1)

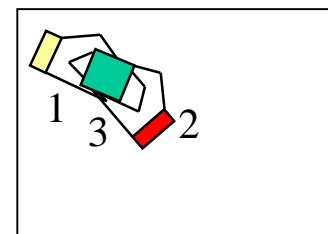


Contact (2, 3)



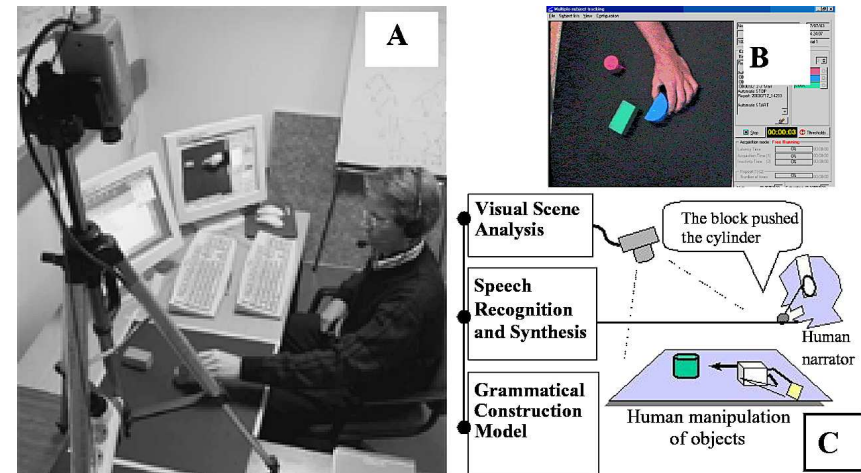
Contact (3, 1)

Contact (2, 1)



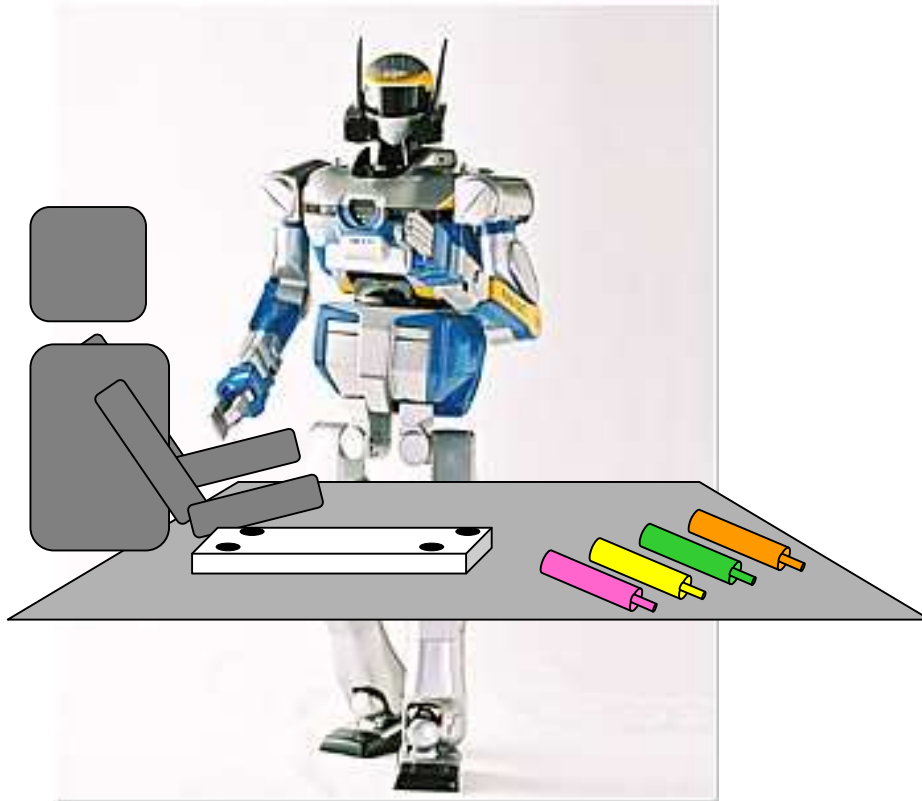
Learning grammatical constructions from naive human subjects in an “unconstrained” situation

- 4 Subjects Generate <Sentence, Meaning> pairs by narrating video events
 - 282 Sentence, meaning pairs:
- Train the model on $\frac{1}{2}$ <Sentence, Meaning> pairs
- Test generalization on second $\frac{1}{2}$
- 85% Accuracy on Training and Test sets



Language in the Context of Cooperation

Cooperative Table Assembly Scenario



- Robot Helps Users to Assemble a Table
- Functional Requirements
 - The robot should be able to:
 - Respond to human spoken commands with simple behaviors
 - Open left hand, turn right,..
 - Grasp(X): X in <visible>
 - Learn complex behaviors constructed from the primitives
 - Give me the orange leg
 - Hold the table

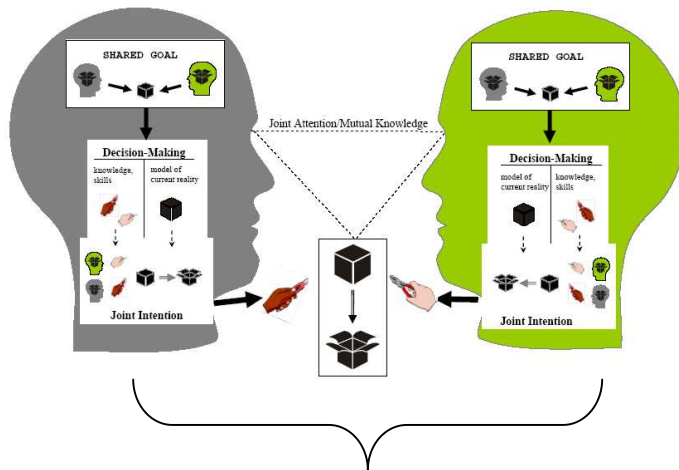
Teach Actions with Grammatical Constructions

- Give me the **green** leg
 - Take the **green** leg
 - Turn right
 - Open right hand
- Training with one example
 - *Green* is passed as an argument to TAKE
 - Learned procedure generalizes over (yellow, rose, green, orange)
 - Powerful learning capability with procedures that take variables
- Embodiment of lexical categories
 - Verbs – procedures
 - Nouns – arguments

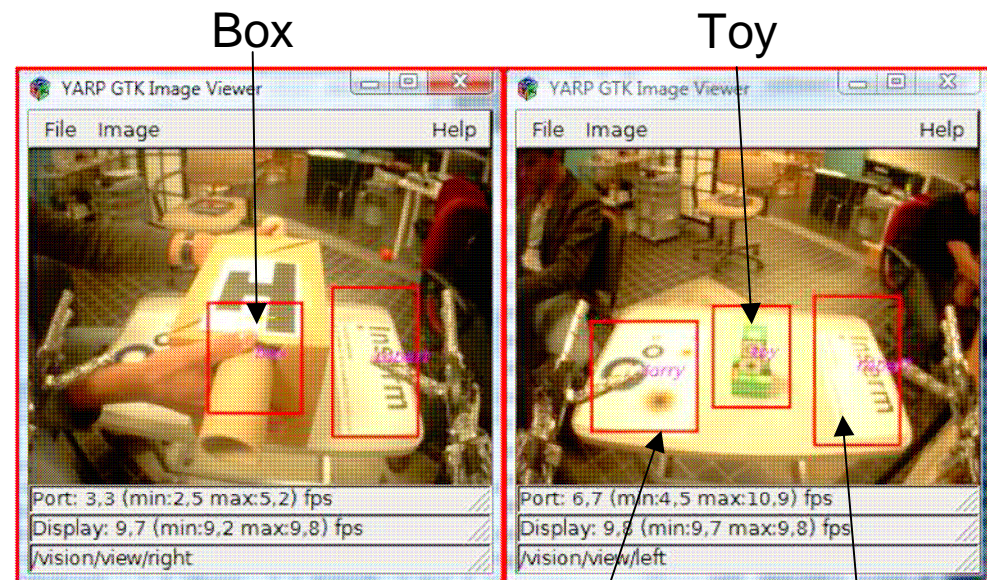


Cooperative Plans from Observation

- Perceive action
- Attribute agency
- Form shared plan
- Use it in cooperation
- Modify the plan with discourse
 - “after, because, if-then ...”

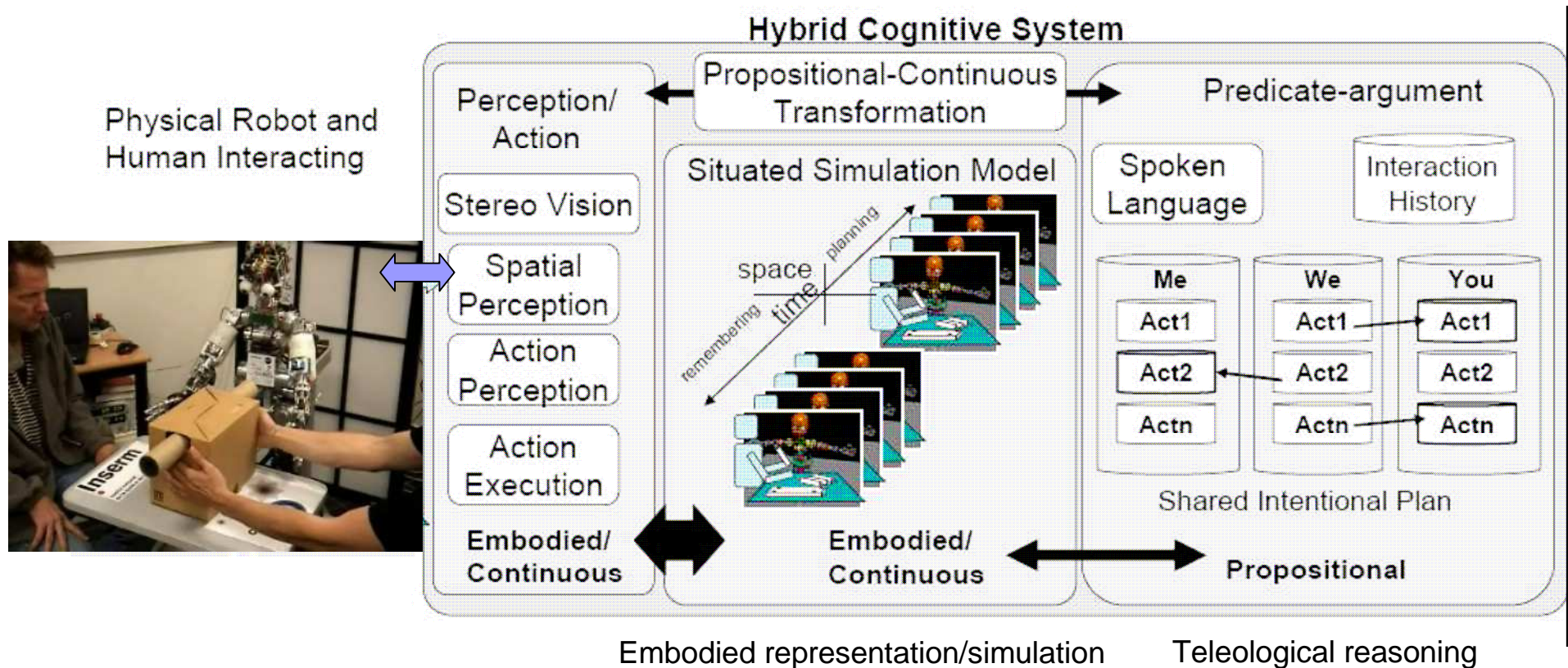


Lallee, Warneken, Dominey (2009)



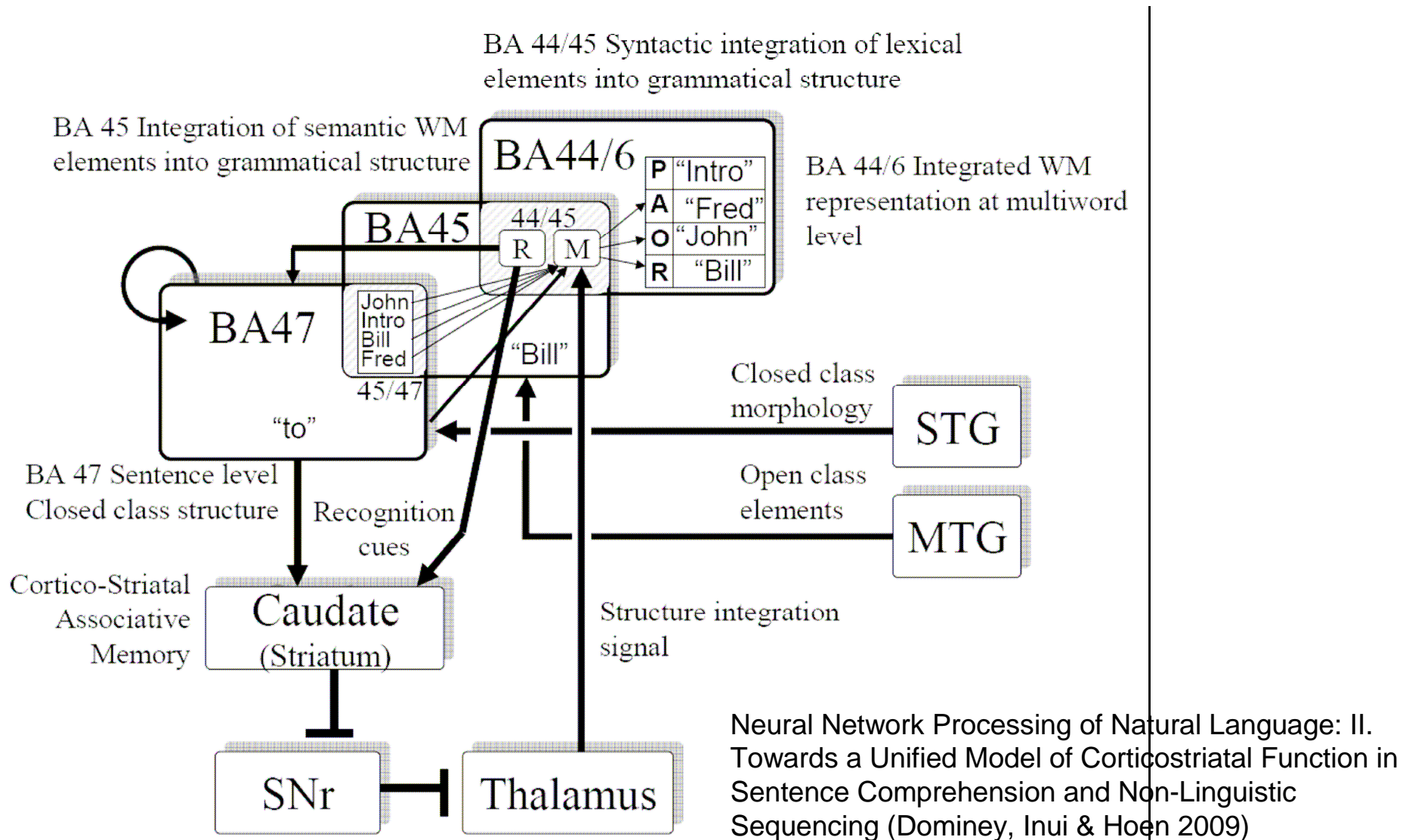
Larry (left) Robert (right)

Perspectives (1) Hybrid Teleological/Embodied Cognitive System

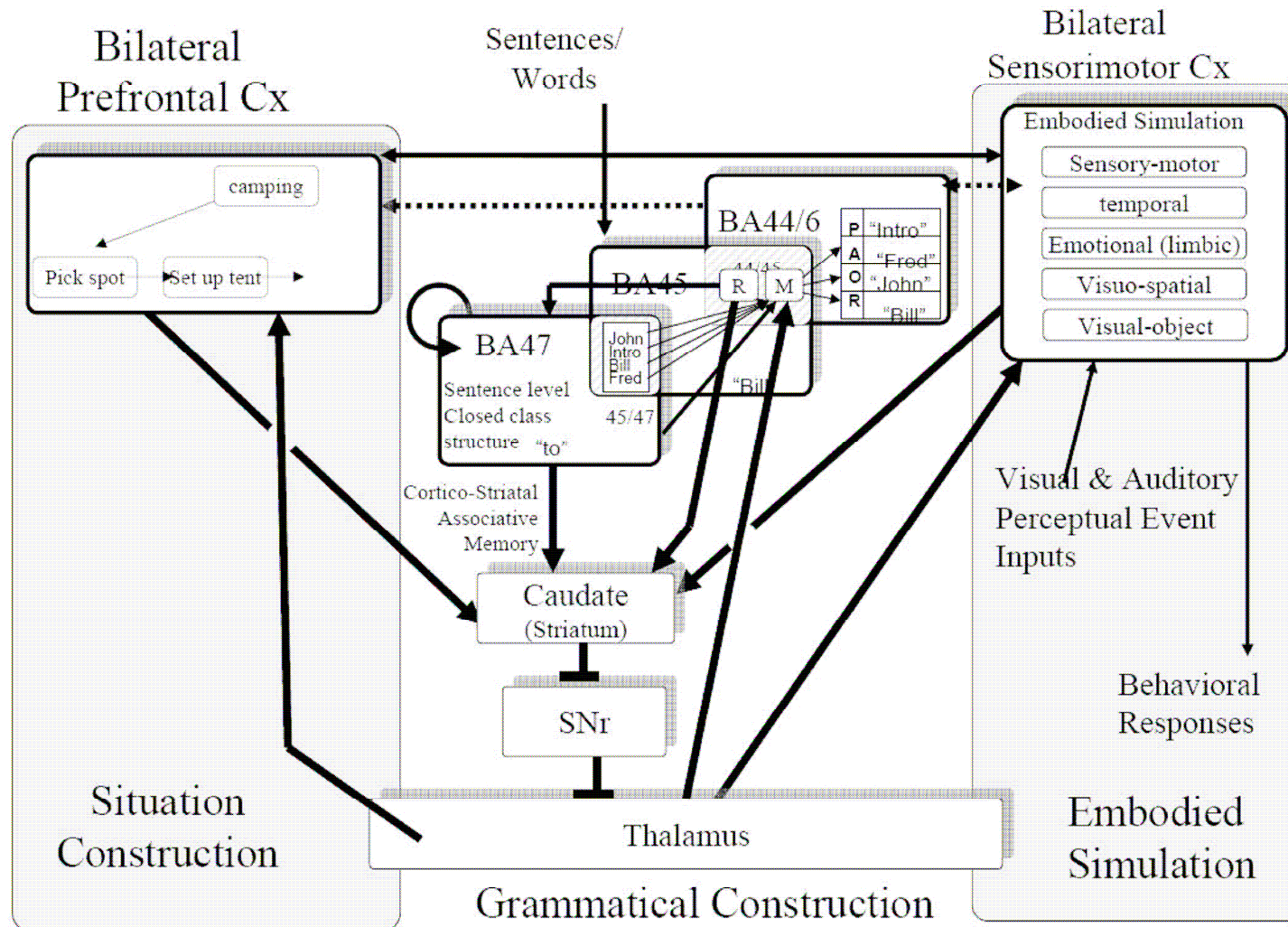


Madden, Hoen, Dominey (2009) Brain and Language
iCub project – Lyon, June 2009

Perspectives (2) Detailed Neurophysiology of On-line sentence processing



Hybrid Comprehension Model



Madden, Hoen, Dominey (2009) Brain and Language



Conclusion & Perspectives

- Requirements on language: what is it for? – Cooperation
 - Linearization of a high dimensional representation
- What strategies can be employed
 - Word order, grammatical markers, prosody, ... Cue Competition
 - Grammatical constructions – form to meaning mapping
- How can this be realized in neurophysiology
 - Specialized working memories in BA47,45,44,6 and the corticostriatal system
 - Link to the embodied representation of meaning
- Perspectives
 - How Is Meaning Generated? From interaction: Enrich the interaction and representation – States, Goals, Causality
 - How does the sensory-motor system participate in learning and comprehension - Embodied language comprehension
 - What is the Underlying Neurophysiology for language learning – linking language to meaning
 - Artificial Systems (robots, neural networks) will play a central role in the study of language acquisition.



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